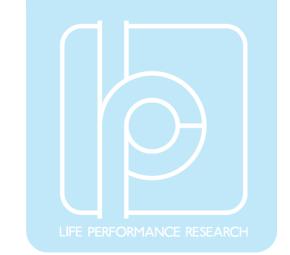
LPMS-IG1W



9-AxisIMU(Inertial Measurement Unit)/AHRS(Pose Measurement)

Wi-Fi communication support

The 9-axis IMU sensor LPMS-IG1W detects orientations and acceleration and measures them with high precision. It is possible to communicate with host systems such as PCs and smartphones via Wi-Fi connection.

The compact size, high accuracy, waterproof case (IP67), and powerful CPU inside the sensor process data from the gyroscope, accelerometer, and magnetometer,

and provide low-drift, high-precision results in real time. It is suitable for industrial environments where highly accurate, low-latency measurements are required.

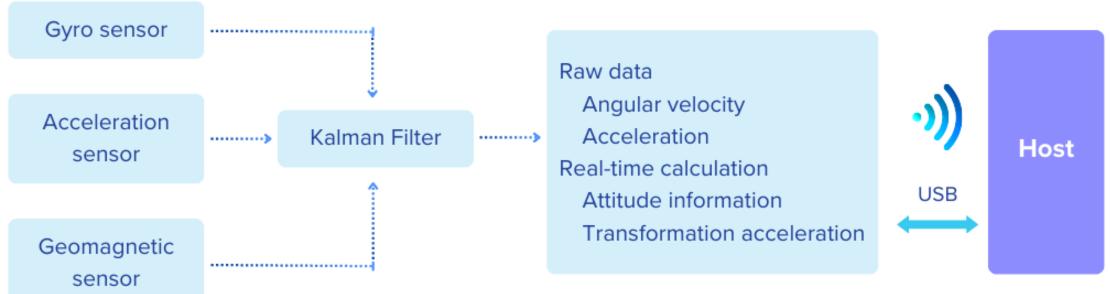


Key Features

- MEMS 9-axis IMU with sensor fusion function
 Equipped with low-noise/low-drift (4°/h)
 accelerometer
- Equipped with two types of gyro, enabling
 measurement over a wide range (400 to 2000°/s)
- Pose/linear acceleration calculated in real time inside sensor
- Wi-Fi connection supported Waterproof (IP67)
 and shock-resistant up to 10,000G. Suitable for industrial environments.

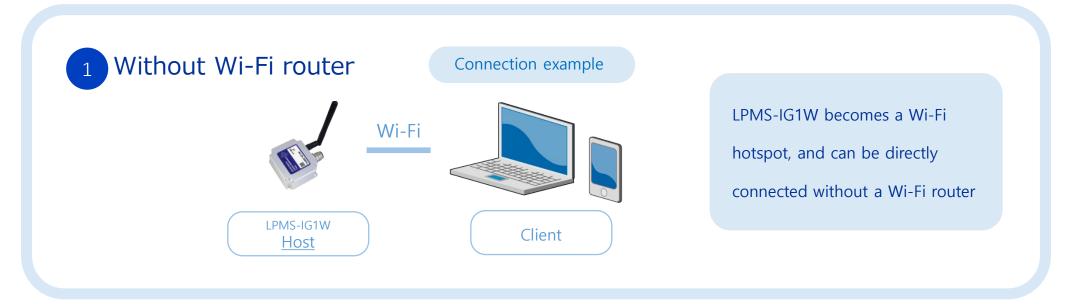
Application

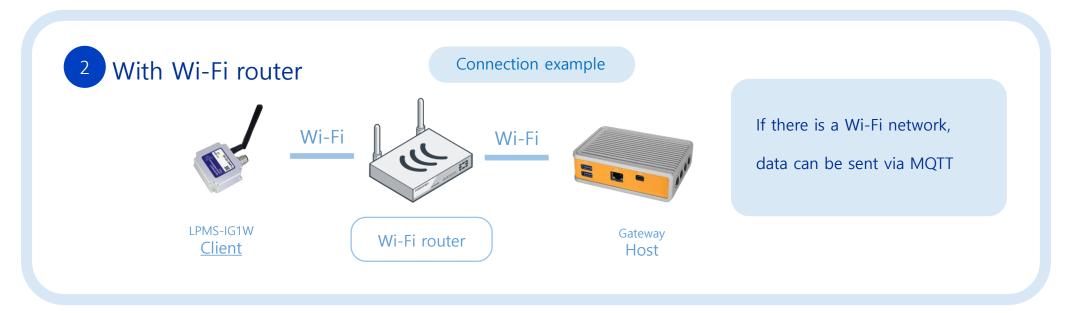
- Remote-controlled robots, robot arms, etc.
- IoT applications such as abnormal vibration detection
- VR/AR tracking systems
- AGV navigation systems





Two types of connection methods





Data Acquisition method

Data can be acquired via socket communication or MQTT



Check sensor data and change settings remotely.

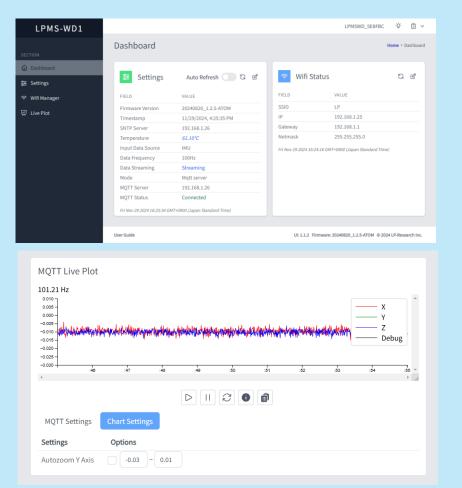
The LPMS-IG1W can host web pages

- This product can host web pages on its own
- Devices on the same network as this product or via a web browser can access it

Remote data confirmation, modification, and operation

- Measurement data from this product can be confirmed in real-time graphs from the hosted web page
- The connection status and temperature of this product can also be confirmed
- Various settings such as the type of data to be acquired and measurement frequency can be changed remotely
- Sensor commands such as the calibration initialization command can also be executed

Example of how it will look in the browser (the screen is still under development)

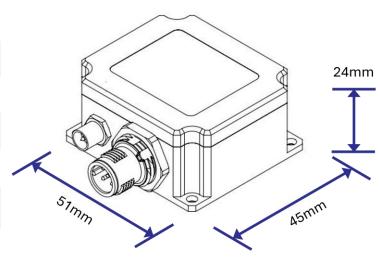


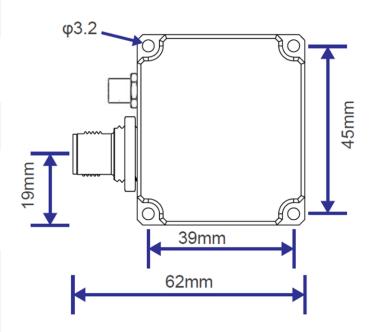
Sensor Specifications

Part number	LPMS-IG1W
Interface	Wi-Fi + USB
Weight	115g
Size	51×45×24mm
Static orientation stability	#1: 4 °/hour, #2: 6 °/hour
Orientation range	360° about all axes
Resolution	< 0.01°
Accuracy	< 0. 3° (static), < 1° RMS (dynamic)
Accelerometer	3-axis, ±20 / ±40 / ±80 / ±160 m/s2, 16 bits
Gyroscope (2 types installed)	Gyro #1: 3-axis, ± 400 dps, 24 bit; Gyro #2: 3-axis, ± 1000 / ± 2000 dps, 16 bit
Magnetometer	3-axis, ± 4 / ± 8 / ± 12 / ± 16 gauss, 16 bits
Gyro-noise density	#1: 0.002 dps/√Hz, #2: 0.004 dps/√Hz
Data output format	Raw data / Euler angle /Quaternion
Data output rate	5 ~ 500 Hz
*Power consumption	0.85W (0.07A@12V)
Power supply	5 V ~ 36 V DC
Temperature range	-20 to +80°C (upon request -40 to +80°C)
Connector	M12 8 Pin (SACC-DSI-MS-8CON-PG 9/0,5 SCO equivalent) SMA connector (antenna connector)
Case material	Aluminum, waterproof (IP67)
Wi-Fi information	Maximum transmission distance: 10 ~ 30m (%1), Wi-Fi frequency band: 2.4GHz, Communication protocol: TCP/IP I MQTT, Wi-Fi output frequency: MQTT 5 ~ 200Hz, Socket 5~500Hz
Coffue	Windows C++ library, Java library for Android,



External Dimensions

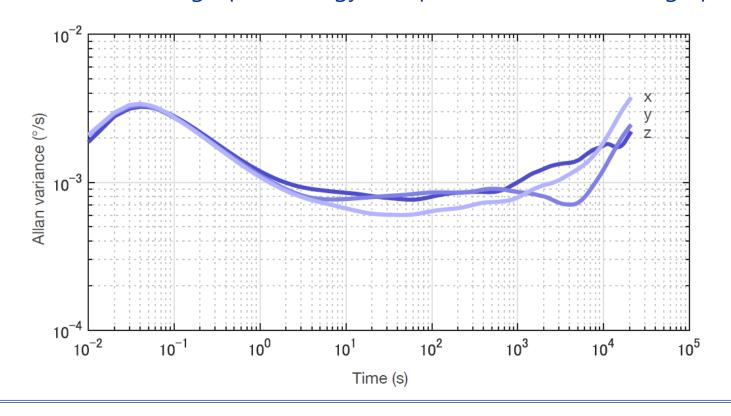




Software

LPMS-IG1W High-precision gyroscope (#1) Allan variance graph

LPMS Control (Data analysis software), Open Motion Analysis Toolkit (OpenMAT) for Windows



<u>Package</u>

- LPMS-IG1W sensor × 1
- Antenna × 1
- Instruction Manual × 1
- Cable (included USB connector)
 × 1
- Warranty (1 year)

 $[\]times 1$: The communication range may change depending on the usage environment.

^{*} Performance parameters are measured at **+25°C**. Other temperatures may result in varying reference values. **Please refer to the product manual for more detailed specifications.