

LPMS-NAV2-RS232

High Accuracy Navigation Sensor with RS232 Interface and Water Proof Housing

LPMS-NAV2-RS232 is a water proof inertial sensor for navigation application, which is composed of a high accuracy one-axis gyroscope and a 3-axis accelerometer. With the use of our novel fusion algorithm, LPMS-NAV2-RS232 can achieve precise heading information with ultra-low drift errors. The output data includes heading angle, angular speed and acceleration via RS232 interface. The high performance and rugged housing design of LPMS-NAV2-RS232 make it specially suitable for industrial applications of mobile robot/vehicle navigation.

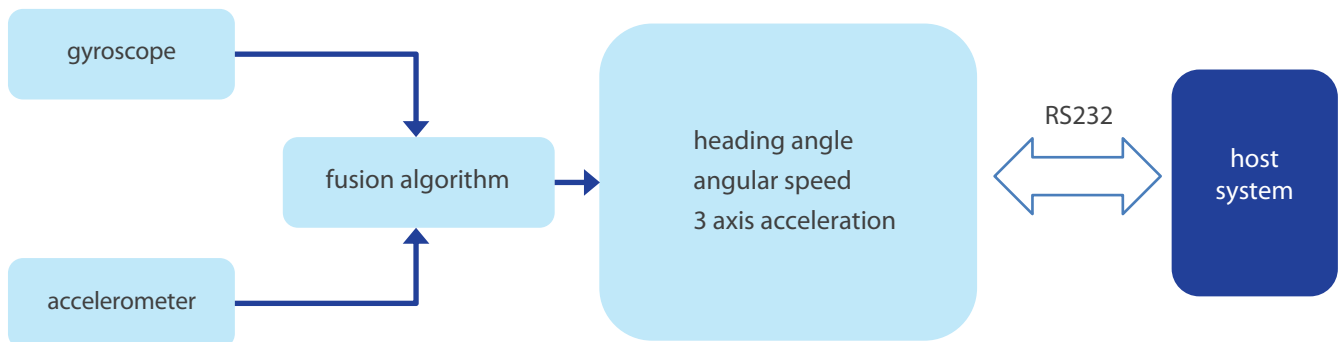


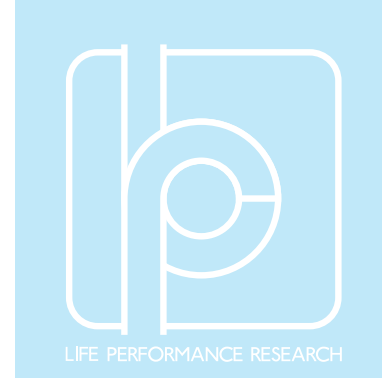
Main Features

- based on MEMS inertial sensors
- integrating one-axis gyro and 3-axis accelerometer
- novel sensor fusion algorithm
- precise heading data output
- low noise
- high robustness
- interface: rs232
- water proof: IP67

Application:

- robotics
- motion capture
- automated guided vehicle (AGV)
- stability control



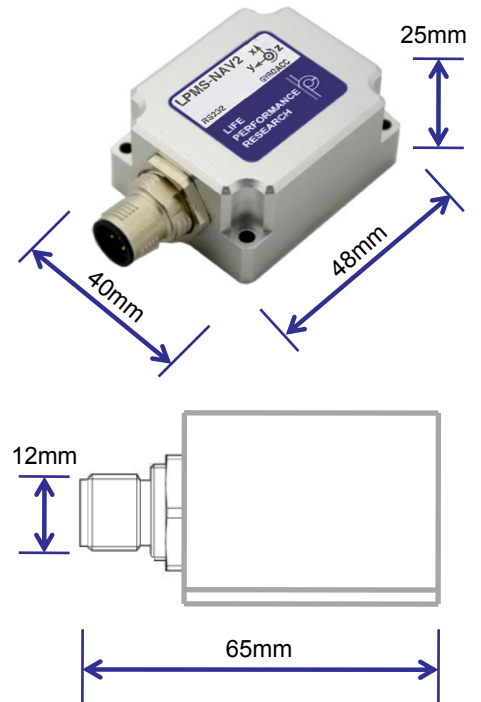


Specifications

Parameter	LPMS-NAV2-RS232
Size	40x48x25mm
Weight	70.1g
Heading range	$\pm 180^\circ / 0 \sim 360^\circ$ (selectable)
Angle resolution	0.01° (Max.)
Angular speed range	± 400 dps
Acceleration range	± 4 g
Data output rate	10~100 Hz selectable
RS232 baudrate	19200~115200bps selectable
Heading linear error	$< 0.1^\circ/m$
Angle random walk (f=10Hz)	0.18°/√h
Bias stability (f=10Hz)	$< 5^\circ/h$
Power consumption	~14mA (@12V)
Power supply	5~18V DC
Water proof	IP67
Housing material	Aluminum
Working temperature	-20~80°C
Stock temperature	-40~85°C

Dimension

LPMS-NAV2-RS232:



Package

- LPMS-NAV2-RS232 sensor x 1
- User guide card x 1
- Water proof cable x 1
- Package box x 1
- Warranty: 1 year



GUI in Windows

